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MANUAL ENGLISH

for the Devices of the MVK-MPNIO Safety Series MVK-MPNIO F DI16/8 Art. No. 55560 and MVK-MPNIO F DI8/4 F DO4 Art. No. 55561



3 Description

3.1 Module

Features

The MVK-MPNIO Safety Module is a fully encapsulated field bus module in a metal case. It is particularly robust and designed for use in rough environments.

Feature	Description		
Robust	Versatile applications under very high loads due to:		
	 rugged metal casing; 		
	 no condensate formation due to fully encapsulated case; 		
	 resistant to weld spatter in combina- tion with rugged metal case; 		
Vibration-proof	Safety function also guaranteed when sub- jected to continuous vibration.		
Resistant	Long service life despite exposure to aggres- sive media due to high-quality surface finish.		
Tight	Tight to IP67 Protection Class (EN60529)		

3.1.1 Technical Data

	Description	Art. No. 55560	Art. No. 55561	
Safety codes	PL up to e		to e	
EN ISO 13849-1,	Category	up to 4		
IEC 61508 and IEC 62061	PFH	1,70E-9	1,653E-9	
	MTTFd	148 Jahre	157 Jahre	
	DC	98%		
	SIL	up to 3		
	<u>SIL CL</u>	up to 3		
	Service life	20 y	ears	
Ambient conditions	Operating temperature	-20°C to	o +55°C	
	range			
	Storage temperature range	-40°C to +70°C		
	Protection Class to EN	IP67		
	60529			
Dus	Transfer rate	100 Mbit/s		
		Via DCP		
Dower ourplu	Operating voltage and	24)		
rower suppry	sensor power supply (US)	24 VDC		
	Actuator power supply (UA)	24 VDC		
	Voltage range US/UA	18 to 30 VDC		
	Max_current at 7/8" sock-	9 4		
	et/plug	3 4		
	Power consumption (without	≤0.16 A		
	inputs)	2		
	Line cross-section 7/8" plug	max. 1.5 mm ²		
	Reverse-connection protec-	Only US	Yes	
	tion for US and UA	(UA not used)		

Description	Art. No. 55560	Art. No. 55561
Delay time	1, 3, 10, or 15 ms	
Input characteristic	DIN EN 61131-2 (IEC 61131-2),	
	Туре 1	
Sensor power supply		
• When Pin 1 and Pin 5	0.2 A per pin	
are used.		
When Pin 1 <u>or</u> Pin 5 is	max. 0.7 A	
used.		
Short-circuit protection for	High Side Switch w	vith overload pro-
sensor power supply	tection	
Line length	-	max. 30 m
(0.34 mm ² and 0.75 mm ²)		
Line cross-section	-	max. 0.75 mm ²

Inputs

Outputs (Art. No. 55561)

Output current	-	max. 2 A per pin,
		Σ8Α
Line length (0.34 mm ² and	-	max. 30 m
0.75 mm²)		
Line cross-section	-	max. 0.75 mm ²
Frequency	-	max. 1 Hz

3.1.2 **PROFINET IO Communication**

PROFINET IO is an open communication protocol that complies with IEC 61784-2. The communication protocol is based on Ethernet.
Data is exchanged between the control unit, referred to as the PROFINET IO Controller, and connected users, which are called PROFINET IO devices.
M12 connectors link the MVK-MPNIO Safety Module to the PROFINET IO network.
Communication is based on a full-duplex Ethernet network running at 100 Mbit/s. IO controllers and IO devices communicate by means of Ethernet telegrams. Devices exchange data cyclically based on the provider-consumer principle. Devices function simultaneously as receiver (consumer) and transmitter (provider).
The IO controller sends output data to the IO devices and receives input data from the IO devices. The IO devices send input data and receive output data.
Other components of the communication protocol include telegrams in the form of acyclical communication to transfer parameters and for read/write access to I&M data or manufacturer-specific features <u>lundM</u> .

3.1.3 PROFIsafe Communication

Safe communication	PROFIsafe is a functionally safe expansion of standard communica- tion via PROFINET or PROFIBUS. Communication based on PROFIsafe is secured against alteration, transmission errors, changes to the telegram sequence, etc.
MVK-MPNIO Safety Module	The MVK-MPNIO Safety Module is a PROFIsafe module and com- plies with "PROFIsafe – Profile for Safety Technology on PROFIBUS DP and PROFINET IO" Version 2.4 of March 2007.
	The module is based on safe communication with a PROFIsafe Master.

3.1.4 Device Design



Fig. 1: Device design of Art. No. 55560 and Art. No. 55561

Legend

- 1 DI, digital inputs, M12 sockets
- 2 Art. No. 55560: DI, digital inputs, M12 sockets Art. No. 55561: DO, digital outputs, M12 sockets
- 3 Power supply POWER IN
- 4 Power supply POWER OUT
- 5 Port 1 PROFINET
- 6 Port 2 PROFINET
- 7 F addressing
- 8 Grounding strap for functional ground

3.1.5 Displays



Fig. 2: Displays on Art. No. 55560 and Art. No. 55561

Legend

- 1 Digital input display
- 2 Art. No. 55560: Digital input display Art. No. 55561: Digital output display
- 3 LNK1/ACT1 LED
- 4 LNK2/ACT2 LED
- 5 Power LED US
- 6 BUS RUN LED
- 7 Power LED U_A
- 8 CfgF LED
- 9 F_Err LED

3.1.6 Connections

DI M12 sockets A-coded	$5 \frac{1}{4} \frac{1}{0} \frac{1}{3} $		Pin 1 Pin 2 Pin 3 Pin 4	UT 0x IN 1x 0 V IN 0x
			Pin 5	UT 1x
DO M12 sockets	$5 \bigcirc 0 \\ 0 \\ 4 \\ 3 \\ 3 \\ 3 \\ 3 \\ 3 \\ 3 \\ 3 \\ 3 \\ 3$		Pin 1 Pin 2	n. c. n. c.
(only Art. No. 55561) A-coded			Pin 3 Pin 4	<u>M</u> x Px
			Pin 5	_ ^
POWER IN, POWER OUT 7/8" connector	$2 \underbrace{4}_{3} \underbrace{4}_{4} \underbrace{5}_{5}$ Power IN	$5 \underbrace{\begin{pmatrix} 0 \\ 0 \\ 0 \\ 4 \end{pmatrix}}^{1}_{3}^{2}$ Power OUT	Pin 1 Pin 2 Pin 3 Pin 4 Pin 5	0 V _{UA} 0 V _{US} ↔ +24 V US / 9 A +24 V UA / 9 A
Port 1, Port 2 M12 sockets D-coded	$5 \frac{1}{4} \frac{1}{3} $		Pin 1 Pin 2 Pin 3 Pin 4	TD + RD + TD- RD-
			Pin 5	n.c.

3.1.7 F Addressing

F address range 1 to 999	$ \begin{array}{c} x \ 100 \ x \ 10 \ x \ 1 \\ \hline \begin{array}{c} & & \\ $	x1 rotary dip switch (ones)x10 rotary dip switch (tens)x100 rotary dip switch (hundreds)	
As-delivered state: switch positions to "0"	Settings	Description	
	0	Not permitted	
	1 to 999	Possible address range	

3.2 Configurable Functions

3.2.1 Safe Output Parameters

A description of safe output parameters is contained in Section 3.2.2.

Parameters	Possible Selections	Presetting
Output enable	enabled	X
Output enable	disabled	
Wire break detection at cur-	enabled	X
rents > 60 mA	disabled	
Readback time for max. period of switch-off test pulse	4 -6-8-10-20-30-40-50-75-100- 150-200-250-300-400-500 ms	4 ms

Tab. 1: Safe output parameters

3.2.2 Description of Safe Output Parameters

Output enable	When an output is disabled, the related ground and positive pins are not supplied with power, even if they are controlled by the PLC.
Wire break detection	When wire break detection is enabled, a current of > 60 mA must flow via the enabled output. If a current of < 60 mA flows, the "Wire break" alarm is signaled for the affected output.



NOTE

Actuators with a current value of <60 mA:

→ You can avoid false alarms by disabling the wire break detection feature.

The "Wire break detection" parameter has no impact on safety codes.

Readback time

Readback time defines the maximum period of a switch-off pulse.

The module uses switch-off pulses to test the switch-off capability of the P and M branches in a connected output. The connected actuator may delay execution of the switch-off pulse due to energy stored in the form of a capacitance or inductance. The readback time must be adapted to prevent the delayed execution of the switch-off pulse from generating an alarm. A connected actuator must possess a certain "electrical or mechanical inertia" to be able to bridge the duration of the switch-off pulse.

3.2.3 Safe Input Parameters

A description of safe input parameters is contained in Section 3.2.4.

Parameters	Possible Selections	Presetting
Enable input channel Pin 2	enabled	X
	disabled	
Enable input channel Pin 4	enabled	Х
	disabled	
Enable test signal to detect	enabled	X
cross-circuit shorts between Pin 5 and Pin 2	disabled	
Enable test signal to detect	enabled	Х
cross-circuit shorts between Pin 1 and Pin 4	disabled	
Sensor analysis	1001	
	1002	X
Sensor valence	1 channel	
	2 channels equivalent	Х
	2 channels antivalent	
Discrepancy error behavior	Supply 0 value	Х
	Supply last valid value	
Discrepancy time	10-20-30-40-50-75-100-200-	400 ms
	400 -750-1000-2500-5000-	
	10000-15000-30000 ms	
Discrepancy error correction	Test 0 signal required	~
	Test 0 Signal not required	X
Input delay (input filter)	1-3-10-15 ms	1 ms
Monitoring time	enabled	
	disabled	X
Stable time filter ¹		
Check time	10-11-12-13-14- 15 -16-17-18- 19-20 s	15 s
Stabilization time	0.6-0.7- 0.8 -0.9-1.0-1.1-1.2-1.3- 1.4-1.5 s	0.8

Tab. 2: Safe input parameters

¹ The stable time filter, comprising the check time and stabilization time parameters, is enabled when the monitoring time is enabled.

4.1.2 Dimensions



Fig. 6: Dimensions

4.1.3 Fitting the Device

CAUTION

Risk of material damage

The fixing screws are dependent on the substrate at the place of installation.

 \rightarrow Use the right screws suitable for the type of substrate.



Fig. 7: Place of installation



Fitting (keep to the sequence indicated)

- → Fit the upper screw M6 to tightening torque of 8 ^{±0.1} Nm (70.8^{±0,9} lbf-in.)
- ➔ Align the case.
- → Fit the lower screw M6 to tightening torque of 8^{±0.1} Nm (70.8^{±0,9} lbf-in.)

Attach grounding strap



Fig. 8: Attach grounding strap

Tighten the ground strap using a conductive screw M4 and washers (see Figure) to a tightening torque of 1.2 ^{±0.2} Nm (10.6^{±1.2} lbf-in.)

4.2 Installing the Module Electrically

WARNING

Danger from electric voltage in machine.

The result may be death or fatal injuries.

- 1. Observe the five safety rules.
- 2. Connect the device to the electrical system.



WARNING

Fire risk from short-circuits

Power supply lines and/or modules damaged by short-circuits may cause overheating and fires.

➔ Provide an intelligent power monitoring system or fuse.

Fuse protection

The fuse must be designed for max. 9 A. Typically, an 8 A fuse is used.

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